

Bargaining Foundations of the Median Voter Theorem

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Outline of talk

- social choice approach
- bargaining model
- stationary equilibria
 - existence, continuity, delay, core equivalence in one dimension
- voting subgames
- main result
- intuition for proof
- technical point
- extensions
- quick conclusion

Social choice approach

N	set of n agents (n odd)*
$X \subseteq \mathfrak{R}^m$	set of alternatives (compact, convex)
$u_i: X \rightarrow \mathfrak{R}$	i 's utility function (cont., strictly concave)*
\tilde{x}_i	i 's ideal point
\mathcal{M}	collection of majority coalitions
M	majority dominance relation: xMy means that $\{i \mid u_i(x) > u_i(y)\} \in \mathcal{M}$

The Social choice approach (cont.)

- The **core**, denoted K , consists of the “unbeaten” alternatives: $x \in K$ if and only if there is no $y \in X$ such that yMx .
- Under our maintained assumptions, if the core is non-empty, then it is a singleton.
- **Median Voter Theorem:** Assume $X \subseteq \mathbb{R}$, and let k satisfy

$$\#\{i \mid \tilde{x}_i < \tilde{x}_k\} < \frac{n}{2}$$

and

$$\#\{i \mid \tilde{x}_i > \tilde{x}_k\} < \frac{n}{2}.$$

Then $K = \{\tilde{x}_k\}$. Moreover, for every $y \in X \setminus K$, \tilde{x}_kMy .

The goal

- We want a general non-cooperative theory of collective decision-making that generates equilibrium predictions even in multiple dimensions.
- Even better if consistent with the median voter theorem in one dimension.
 - characterization of equilibrium outcomes
 - non-cooperative underpinning of cooperative solution

Bargaining literature

- Rubinstein (1982)
- Binmore (1987)
- Baron and Ferejohn (1989)
- Banks and Duggan (2000, 2003)

Bargaining framework

N	set of n agents (n odd)*
$X \subseteq \mathbb{R}^m$	set of alternatives (compact, convex)
$u_i: X \rightarrow \mathbb{R}$	i 's stage utility function (cont., strictly concave)*
q	status quo
δ	discount factor (common, less than one)*
ρ_i	recognition probability (positive, fixed)*

Bargaining protocol in period t

- an agent i is selected with probability ρ_i to propose, say, x
- each agent j votes accept (a) or reject (r)
- if $\{j \mid v_j = a\} \in \mathcal{M}$, then the game ends with outcome (x, t) , and payoffs are

$$(1 - \delta)^{t-1}u_j(q) + \delta^{t-1}u_j(x)$$

- otherwise, the game continues to period $t + 1$ and is repeated
- if the game continues ad infinitum, then payoffs are $u_j(q)$

Bargaining protocol (cont.)

- Think of payoffs from (x, t) as the discounted sum of the flow of payoffs

$$\underbrace{u_i(q) \ u_i(q) \ \cdots \ u_i(q)}_{t-1 \text{ periods}} \quad \underbrace{u_i(x) \ u_i(x) \ u_i(x) \ \cdots}_{\text{ad infinitum}}$$

Two models of status quo

- (A) the status quo is just an alternative, $q \in X$
- (B) the status quo is “bad,” i.e., for all $i \in N$ and all $x \in X$, $u_i(x) \geq u_i(q)$.

Stationary strategies

$p_i \in X$	pure proposal strat.
$\pi_i \in \mathcal{P}(X)$	mixed proposal strat.
$A_i \subseteq X$	acceptance set
$A_C = \bigcap_{i \in C} A_i$	accept. set for C
$A = \bigcup_{C \in \mathcal{M}} A_C$	social accept. set
$v_i(\sigma)$	continuation value
$(1 - \delta)u_i(q) + \delta v_i(\sigma)$	reservation value

Stationary strategies (cont.)

- We say σ exhibits **delay** if, for some $i \in N$,

$$\pi_i(X \setminus A) > 0.$$

Otherwise, it is **no delay**.

- Under (A), we say σ is **static** if, for all $i \in N$,

$$\pi_i(A \setminus \{q\}) = 0.$$

Stationary equilibria

- Voting strategies are stage-game undominated: for all $i \in N$,

$$A_i^* = \{x \mid u_i(x) \geq (1 - \delta)u_i(q) + \delta v_i(\sigma^*)\}.$$

- Proposal strategies are optimal: for all $i \in N$,

$$\pi_i^*(\arg \max\{u_i(y) \mid y \in A^*\}) = 1$$

whenever

$$\begin{aligned} & \sup\{u_i(y) \mid y \in A^*\} \\ & > (1 - \delta)u_i(q) + \delta v_i(\sigma^*), \end{aligned}$$

and so on.

One-dimensional example

- Let $n = 3$, even chance recognition probabilities, quadratic utilities.

$$\Delta = \sqrt{\frac{(1 - \delta)(\tilde{x}_2 - q)^2}{1 - 2\delta/3}}.$$

- Note
 - unique stationary equilibrium, no-delay, pure strategies
 - $\delta \rightarrow 1$ implies $\Delta \rightarrow 0$
 - $q \rightarrow \tilde{x}_2$ implies $\Delta \rightarrow 0$

Existence and continuity

- **Theorem:** There exists a no-delay stationary equilibrium.
- **Theorem:** If $X \subseteq \mathfrak{R}$, then every no-delay stationary equilibrium is in pure strategies.
- **Theorem:** The correspondence of no-delay stationary equilibrium mixed proposal strategies is upper hemicontinuous in the parameters of the model.

Delay

- **Theorem:** Under (B), all stationary equilibria are no-delay.
- Remark: The above result does not rely on strict concavity.
- **Theorem:** Assume $\delta > 0$. Under (A), if σ is a stationary equilibrium, then σ is static or no-delay.
- Remark: Under (A), delay may occur if $\delta = 0$ or if agents are risk neutral.

Delay (cont.)

- **Theorem:** Under (A), there exists a static stationary equilibrium if and only if $q \in K$.
- Thus,
 - when the core is empty (in multiple dimensions), every stationary equilibrium is no-delay.
 - in one dimension, unless $q \in K$, no stationary equilibrium is static, so all stationary equilibria are no-delay.
- **Theorem:** Assume $X \subseteq \mathfrak{R}$ and $\delta > 0$. If $q \notin K$, then $q \notin A^*$ in every stationary equilibrium.

Uniqueness in one dimension

- **Theorem:** Assume $X \subseteq \mathfrak{R}$ and each u_i is quadratic. There is a unique no-delay stationary equilibrium.
- **Theorem:** Assume $X \subseteq \mathfrak{R}$. If $\hat{\sigma}$ and $\tilde{\sigma}$ are stationary equilibria, then either $\hat{A} \subseteq \tilde{A}$ or $\tilde{A} \subseteq \hat{A}$.
- Thus, there is a unique minimal and a unique maximal no-delay stationary equilibrium.
- Remark: With non-quadratic utilities, there may be multiple no-delay stationary equilibria.

Core equivalence in one dimension

- **Asymptotic Median Voter Theorem I:**
Assume $X \subseteq \mathfrak{R}$. Let $\delta^m \rightarrow 1$, and let $\{\sigma^m\}$ be a sequence of stationary equilibria. Then $A^m \rightarrow K$.
- **Asymptotic Median Voter Theorem II:**
Assume $X \subseteq \mathfrak{R}$ and $\delta > 0$. Let σ^* be any stationary equilibrium. Under (A),
 - if $\{q\} \neq K$, then $q \notin A^*$
 - if $\{q\} = K$, then $A^* = \{q\}$, so the status quo is the unique stationary equilibrium outcome
 - if $q \rightarrow K$, then $A^* \rightarrow K$.

Folk theorems in bargaining

- Let X be the unit simplex in \mathbb{R}^n , so $x = (x_1, \dots, x_n)$ is an allocation of a “dollar” to the agents. Let $u_i(x) = x_i$. Then every allocation can be supported as a subgame perfect equilibrium outcome when the agents are patient enough in...
 - the multi-agent Rubinstein bargaining model
 - the Baron-Ferejohn model of majority bargaining.
- Is stationarity critical for the asymptotic median voter results? Is there a folk theorem for the one-dimensional bargaining model?

Continuation lotteries

- We can summarize future play by a “continuation lottery.”
- For example, suppose in odd periods, there is a $1/3$ chance that x passes and $2/3$ chance of delay; in even periods, there is a $1/4$ chance of x' and $3/4$ chance of delay.
- Then agent i 's expected payoff U_i at the beginning of period 1 satisfies:

$$\begin{aligned} \frac{U_i}{1 - \delta} &= \frac{1}{3} [u_i(x) + \delta u_i(x) + \dots] \\ &+ \frac{2}{3} \left[u_i(q) + \frac{\delta}{4} [u_i(x') + \delta u_i(x') + \dots] \right. \\ &\left. + \frac{3\delta}{4} \left[u_i(q) + \frac{\delta U_i}{1 - \delta} \right] \right] \end{aligned}$$

Continuation lotteries (cont.)

- Then agent i 's expected payoff U_i at the beginning of period 1 can be written as

$$U_i = \alpha u_i(x) + \beta u_i(x') + \gamma u_i(q)$$

where

$$\alpha = \frac{2}{6 - 3\delta^2}$$
$$\beta = \frac{\delta}{6 - 3\delta^2}$$
$$\gamma = \frac{4 - \delta - 3\delta^2}{6 - 3\delta^2}$$

and

$$\alpha + \beta + \gamma = 1.$$

- That is, $U_i = E_\lambda[u_i]$, where λ is the continuation lottery on X .

Voting subgames

- In stationary equilibria, the voting game reduces to a binary vote, and stage-game weak dominance is effective.
- Suppose x has been proposed.

	a	r
a	x	x
r	x	λ
	a	

	a	r
a	x	λ
r	λ	λ
	r	

If row strictly prefers x to continuing, then voting r is weakly dominated in the stage game.

- In fact, x survives elimination if and only if it is weakly majority-preferred to continuing.

Voting subgames (cont.)

- Not so when stationarity is dropped.

	<i>a</i>	<i>r</i>
<i>a</i>	<i>x</i>	<i>x</i>
<i>r</i>	<i>x</i>	λ_1
	<i>a</i>	

	<i>a</i>	<i>r</i>
<i>a</i>	<i>x</i>	λ_2
<i>r</i>	λ_3	λ_4
	<i>a</i>	<i>r</i>

- Suppose payoffs are as follows.

row	column	matrix
λ_1	λ_2	λ_3
<i>x</i>	<i>x</i>	<i>x</i>
λ_4	λ_4	λ_4
λ_2	λ_3	λ_1

Then λ_4 is a strict (therefore undominated) Nash equilibrium outcome, but all agents strictly prefer *x*.

Voting subgames (cont.)

- We model voting as **sequential**: this allows us to drop the stage-game weak dominance refinement and leaves stationary equilibrium outcomes unchanged.
- A **key property** we want: the median \tilde{x}_k passes with positive probability if it is proposed.
- For this, we assume:
 - The order of voting is determined randomly after the proposer is determined.
 - Every order of voting has a positive, fixed* probability.

Subgame perfect equilibria

- A strategy σ is a pure strategy subgame perfect equilibrium if there do not exist an agent, a history, and a deviation from σ that increases that agent's expected payoff following that history.
- Let $X(\delta)$ consist of alternatives x such that:
 - there exists a proposer history h and a pure strategy subgame perfect equilibrium σ such that x passes with positive probability from h in σ .
- Let $V_i(\delta)$ consist of payoffs r such that:
 - there exists a proposer history h and a pure strategy subgame perfect equilibrium σ such that i 's expected payoff is r from h in σ .

Main result

- Given a sequence of sets $\{Y^m\}$ in Euclidean space and an element x , we write $Y^m \rightarrow x$ if $\sup_{y \in Y^m} \|y - x\| \rightarrow 0$.
- **Asymptotic MVT I:** Let $\{\delta^m\}$ be a sequence of discount factors converging to one. Then
 - $X(\delta^m) \rightarrow \tilde{x}_k$,
 - for all $i \in N$, $V_i(\delta^m) \rightarrow u_i(\tilde{x}_k)$.
- That is,
 - subgame perfect equilibrium outcomes converge to the median ideal point,
 - equilibrium delay becomes negligible.

Intuition for proof (cont.)

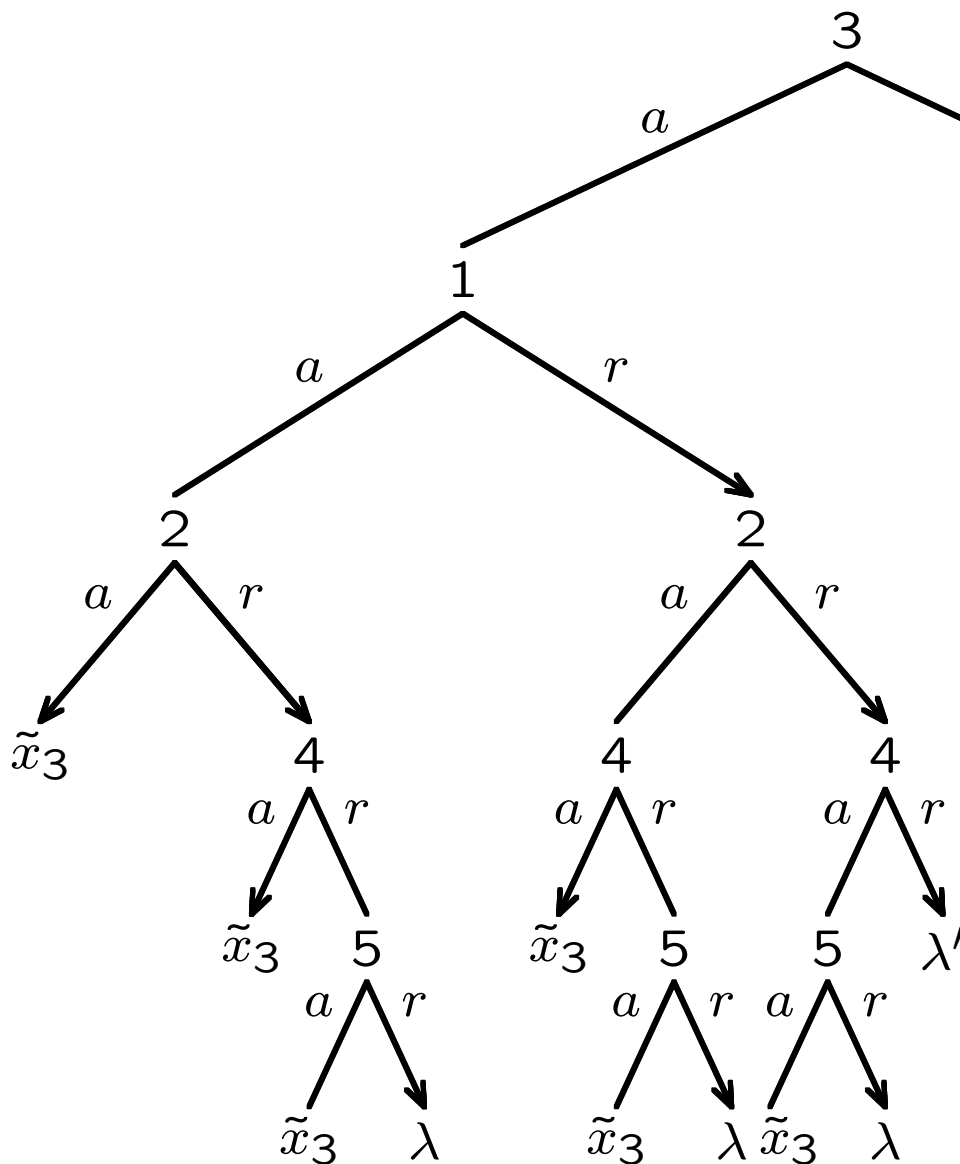
- **Lemma:** Suppose $x \in X(\delta^m)$ is proposed in some equilibrium and passes with positive probability. Then there is an agent i^m in C^m who weakly prefers x to the continuation lottery from rejecting the proposal.
- Apply the lemma with $x = \bar{x}^m$ to get an agent i^m from each C^m who weakly prefers \bar{x}^m to the continuation lottery from rejection. But...
- **Lemma:** In every subgame perfect equilibrium, if the median \tilde{x}_k is proposed, then it passes with positive probability (bounded above zero).

Intuition for proof (cont.)

- As a consequence, agent i^m can obtain the median with positive probability when selected to propose.
- So why would the agent i^m be willing to vote for his/her worst alternative rather than reject it and at least obtain the median \tilde{x}_k with positive probability?
- It must be that the status quo is inferior to \bar{x}^m , and that delay makes the agent worse off.
- But we show that, as the agent becomes patient, delay becomes inconsequential, a contradiction.

Subtle technical point

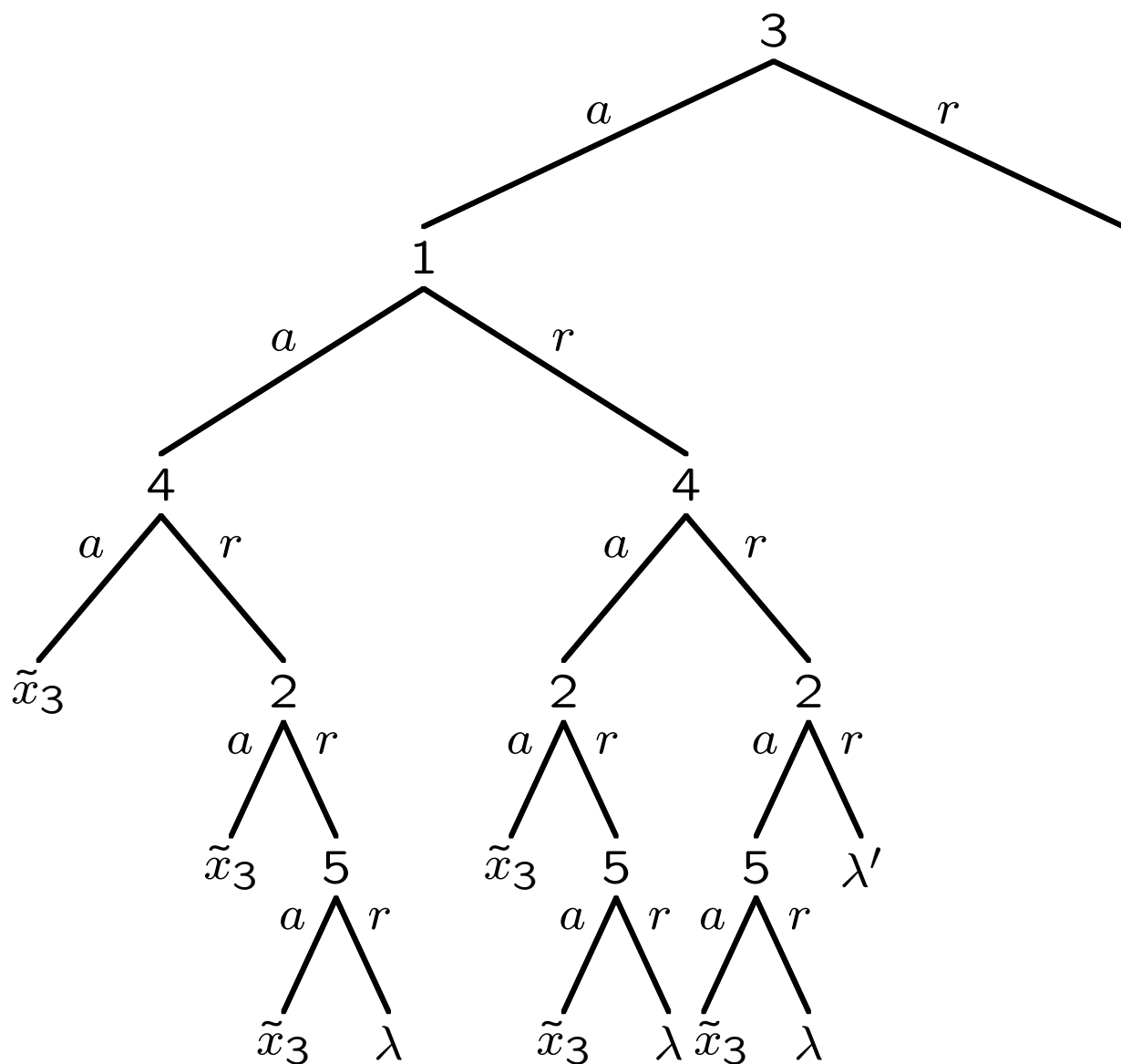
- Let ideal points of 1, 2, 3, 4, 5 be in order of voter indices. Suppose the median \tilde{x}_3 is proposed and 3 has voted a ...



1	2	4	5
λ'	λ'	\tilde{x}_3	λ
\tilde{x}_3	\tilde{x}_3	λ'	\tilde{x}_3
		λ	

Technicality (cont.)

- Now suppose the voting order alternates...



Technicality (cont.)

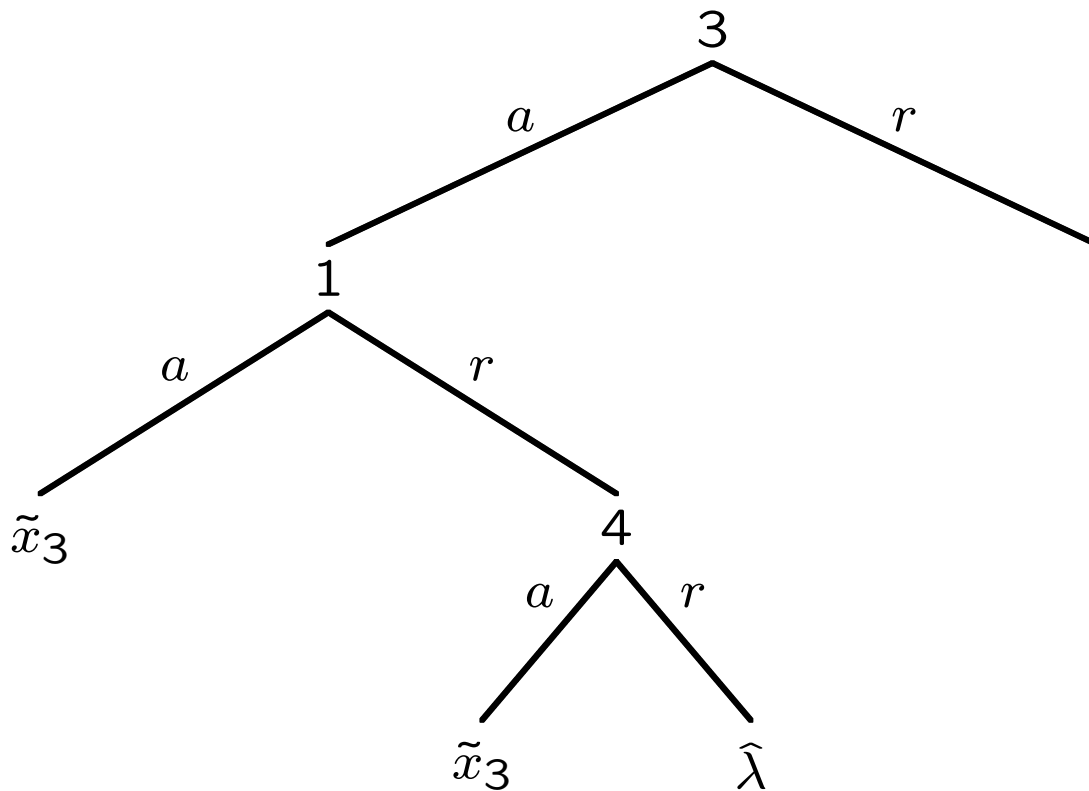
- By concavity, if agent 5 weakly prefers λ to the median \tilde{x}_3 , and if agent 2 has the same weak preference, then the mean of λ must be equal to \tilde{x}_3 .

- By strict concavity, the continuation lottery λ must have zero variance, so it is the point mass on \tilde{x}_3 .

- Therefore, the only possible equilibrium outcome of the first two 2:5 voting subgames is the median.

Technicality (cont.)

- Then the game reduces to...



... and the same logic applies.

- Therefore, the median voter can (and will) obtain her ideal point by voting a in equilibrium.

Extensions of Main Result

- Even number of agents: okay, but we need one of the median voters to “break ties.”
- Concavity: strict concavity can be weakened to allow for piece-wise linear.
- Heterogeneous discount factors: we just need discount factors to converge to one at a “uniform enough” rate, i.e.,

$$\frac{\ln(\delta_i^m)}{\ln(\delta_j^m)} \rightarrow 1$$

for all $i, j \in N$.

Extensions (cont.)

- Variable recognition probabilities: These can vary arbitrarily with histories, as long as each agent's probability is bounded strictly above zero.
- Variable probability of voting orders: Can vary arbitrarily with histories, as long as voting alternates with probability bounded strictly above zero.
- Mixed strategy equilibria: mixed proposal strategies are not a problem; mixed voting strategies introduce some difficulties.
- Asymptotic MVT II. . .

Quick conclusion

- In contrast to the “divide the dollar” model of bargaining, an anti-folk theorem holds for the one-dimensional model.
- The asymptotic MVT I for stationary equilibria extends quite generally.
- Delay becomes negligible as agents become patient.